

The entry sum of the inverse Cauchy matrix

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1. The Cauchy matrix

Let x_1, x_2, \dots, x_n be n numbers, and y_1, y_2, \dots, y_n be n further numbers chosen such that all n^2 pairwise sums $x_i + y_j$ are nonzero¹. Consider the $n \times n$ -matrix

$$C := \left(\frac{1}{x_i + y_j} \right)_{1 \leq i \leq n, 1 \leq j \leq n} = \begin{pmatrix} \frac{1}{x_1 + y_1} & \frac{1}{x_1 + y_2} & \cdots & \frac{1}{x_1 + y_n} \\ \frac{1}{x_2 + y_1} & \frac{1}{x_2 + y_2} & \cdots & \frac{1}{x_2 + y_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{x_n + y_1} & \frac{1}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} \end{pmatrix}.$$

This matrix C is known as the *Cauchy matrix*, and has been studied for 180 years². The first significant result was the formula for its determinant:

$$\det C = \frac{\prod_{1 \leq i < j \leq n} ((x_i - x_j)(y_i - y_j))}{\prod_{(i,j) \in \{1,2,\dots,n\}^2} (x_i + y_j)} \quad (1)$$

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¹Algebraists can replace the words “number” and “nonzero” by “element of a commutative ring” and “invertible”, respectively. This generalization comes for free; we will not use anything specific to any kind of numbers in our proofs.

²Many authors define it to have entries $\frac{1}{x_i - y_j}$ instead of $\frac{1}{x_i + y_j}$. This boils down to replacing y_1, y_2, \dots, y_n by $-y_1, -y_2, \dots, -y_n$.

found by Cauchy in 1841 [1] (see, e.g., [11, §1.3] or [2, Exercise 6.18 or Exercise 6.64] for modern proofs). Newer research focuses, e.g., on the LU decomposition [5], positivity properties [4], or generalizations [7]. See [6] for more on the history of the topic and for its connections to Lagrange interpolation (and for another proof of (1)). Applications range from the theoretical (an equivalent version [3, Lemma 5.15.3] of (1) is used in the classical representation theory of symmetric groups) to the practical (computing the inverse C^{-1} is a notoriously ill-conditioned problem that is used as a canary for numerical instability [13]).

2. The sum of the entries of the inverse

The following curious result appears to be known since at least the 1940s:

Theorem 2.1. Assume that the matrix C is invertible. Then, the sum of all entries of its inverse C^{-1} is $\sum_{k=1}^n x_k + \sum_{k=1}^n y_k$.

A natural, yet laborious approach to proving this theorem is to compute the entries of C^{-1} using (1), and then to add them up. The resulting sum can be seen (by a tricky induction) to simplify to $\sum_{k=1}^n x_k + \sum_{k=1}^n y_k$. Some details of this proof can be found in [8, §1.2.3, Exercise 44]. The proof given in [12, (13)] is simpler, avoiding the use of (1) but relying on Lagrange interpolation theory instead.

We propose a new proof of Theorem 2.1, which reflects the simplicity of the theorem. We let $A_{i,j}$ denote the (i,j) -th entry of any matrix A . The following simple lemma gets us half the way:

Lemma 2.2. Let A be an $n \times m$ -matrix, and let B be an $m \times n$ -matrix. Then,

$$\sum_{i=1}^n \sum_{j=1}^m (x_i + y_j) A_{i,j} B_{j,i} = \sum_{i=1}^n x_i (AB)_{i,i} + \sum_{j=1}^m y_j (BA)_{j,j}.$$

Proof of Lemma 2.2. We have

$$\begin{aligned}
 \sum_{i=1}^n \sum_{j=1}^m (x_i + y_j) A_{i,j} B_{j,i} &= \sum_{i=1}^n \sum_{j=1}^m x_i A_{i,j} B_{j,i} + \underbrace{\sum_{i=1}^n \sum_{j=1}^m y_j A_{i,j} B_{j,i}}_{= \sum_{j=1}^m \sum_{i=1}^n y_j B_{j,i} A_{i,j}} \\
 &= \sum_{i=1}^n \sum_{j=1}^m x_i A_{i,j} B_{j,i} + \sum_{j=1}^m \sum_{i=1}^n y_j B_{j,i} A_{i,j} \\
 &= \sum_{i=1}^n x_i \underbrace{\sum_{j=1}^m A_{i,j} B_{j,i}}_{=(AB)_{i,i} \text{ (by the definition of the matrix product)}} + \sum_{j=1}^m y_j \underbrace{\sum_{i=1}^n B_{j,i} A_{i,j}}_{=(BA)_{j,j} \text{ (by the definition of the matrix product)}} \\
 &= \sum_{i=1}^n x_i (AB)_{i,i} + \sum_{j=1}^m y_j (BA)_{j,j}.
 \end{aligned}$$

□

Proof of Theorem 2.1. Applying Lemma 2.2 to $m = n$, $A = C$ and $B = C^{-1}$, we obtain

$$\begin{aligned}
 \sum_{i=1}^n \sum_{j=1}^n (x_i + y_j) C_{i,j} (C^{-1})_{j,i} &= \sum_{i=1}^n x_i \underbrace{(CC^{-1})_{i,i}}_{=1 \text{ (since } CC^{-1} \text{ is the identity matrix)}} + \sum_{j=1}^n y_j \underbrace{(C^{-1}C)_{j,j}}_{=1 \text{ (since } C^{-1}C \text{ is the identity matrix)}} \\
 &= \sum_{i=1}^n x_i + \sum_{j=1}^n y_j = \sum_{k=1}^n x_k + \sum_{k=1}^n y_k.
 \end{aligned}$$

However, the factor $(x_i + y_j) C_{i,j}$ on the left hand side of this equality simplifies to 1 (since the definition of C yields $C_{i,j} = \frac{1}{x_i + y_j}$). Thus, the left hand side of this

equality is $\sum_{i=1}^n \sum_{j=1}^n \underbrace{(x_i + y_j) C_{i,j}}_{=1} (C^{-1})_{j,i} = \sum_{i=1}^n \sum_{j=1}^n (C^{-1})_{j,i}$, which is clearly the sum of all entries of C^{-1} . We have thus shown that the sum of all entries of C^{-1} is $\sum_{k=1}^n x_k + \sum_{k=1}^n y_k$. This proves Theorem 2.1. □

3. Variants

Theorem 2.1 was stated under the assumption that C be invertible. Using (1), it is easy to see that this assumption is equivalent to requiring that x_1, x_2, \dots, x_n be

distinct and that y_1, y_2, \dots, y_n be distinct³. It is not hard to relieve Theorem 2.1 of this assumption: Just replace the inverse C^{-1} (which no longer exists) by the adjugate⁴ $\text{adj} C$ of the matrix C . The resulting theorem is as follows:

Theorem 3.1. The sum of all entries of the adjugate matrix $\text{adj} C$ is $\left(\sum_{k=1}^n x_k + \sum_{k=1}^n y_k \right) \det C$.

Proof. Similar to our above proof of Theorem 2.1.⁵ Use the classical result that $C \cdot \text{adj} C = \text{adj} C \cdot C = \det C \cdot I_n$ (where I_n denotes the $n \times n$ identity matrix). \square

Theorem 3.1 can be transformed even further:

Theorem 3.2. Let D be the $(n+1) \times (n+1)$ -matrix obtained from C by inserting a row full of 1's at the very bottom and a column full of 1's at the very right, and putting 0 in the bottom-right corner:

$$D = \begin{pmatrix} \frac{1}{x_1 + y_1} & \frac{1}{x_1 + y_2} & \cdots & \frac{1}{x_1 + y_n} & 1 \\ \frac{1}{x_2 + y_1} & \frac{1}{x_2 + y_2} & \cdots & \frac{1}{x_2 + y_n} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \frac{1}{x_n + y_1} & \frac{1}{x_n + y_2} & \cdots & \frac{1}{x_n + y_n} & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{pmatrix}.$$

Then,

$$\det D = - \left(\sum_{k=1}^n x_k + \sum_{k=1}^n y_k \right) \cdot \det C.$$

Proof sketch. This follows from Theorem 3.1 using the following more general fact: If A is any $n \times n$ -matrix, and if B is the $(n+1) \times (n+1)$ -matrix obtained from A in the same way as D was obtained from C (that is, by inserting a row full of 1's at the very bottom and a column full of 1's at the very right, and putting 0 in the bottom-right corner), then

$$\det B = -s,$$

³Algebraists working over an arbitrary commutative ring should read "distinct" as "strongly distinct" (where two elements a, b of a ring are said to be *strongly distinct* if their difference $a - b$ is invertible).

⁴The *adjugate* $\text{adj} A$ of an $n \times n$ -matrix A is the $n \times n$ -matrix whose (i, j) -th entry is $(-1)^{i+j} \det(A_{\sim j, \sim i})$, where $A_{\sim j, \sim i}$ is the result of removing the j -th row and the i -th column from A . Older texts often refer to the adjugate as the "classical adjoint" (or just as the "adjoint", which however has another meaning as well).

⁵I wrote up this proof in much more detail in [2, solution to Exercise 6.69 (a)].

where s is the sum of all entries of $\text{adj } A$. This fact, in turn, can be proved by Laplace expansion of $\det B$ along the last row (followed by expanding each cofactor along the last column). We refer to [2, solution to Exercise 6.69 (c)] for all details. \square

Theorem 3.2 appears in [9, Chapter XI, Exercise 43]; we know nothing more about its origins.

4. Two little exercises

For all its aid in our proof, it appears that Lemma 2.2 is a one-trick pony: We are unaware of any other interesting results whose proofs it simplifies. The sum of all entries of a matrix is not generally a particularly well-behaved quantity (unlike the sum of its **diagonal** entries, which is known as the trace and has many good properties). However, some experimentation has led us to a surprising (if not very deep) twin to Theorem 2.1.

We assume that x_1, x_2, \dots, x_n and y_1, y_2, \dots, y_n are **real** numbers (and that $n \geq 1$). Consider the $n \times n$ -matrix

$$F := (\min \{x_i, y_j\})_{1 \leq i \leq n, 1 \leq j \leq n} = \begin{pmatrix} \min \{x_1, y_1\} & \min \{x_1, y_2\} & \cdots & \min \{x_1, y_n\} \\ \min \{x_2, y_1\} & \min \{x_2, y_2\} & \cdots & \min \{x_2, y_n\} \\ \vdots & \vdots & \ddots & \vdots \\ \min \{x_n, y_1\} & \min \{x_n, y_2\} & \cdots & \min \{x_n, y_n\} \end{pmatrix}.$$

Thus, F is obtained from C by replacing the “inverted sums” $\frac{1}{x_i + y_j}$ by the minima $\min \{x_i, y_j\}$ ⁶. It would almost be too much to ask for F^{-1} to have properties comparable to those of C^{-1} . But in fact, it behaves even better:

Proposition 4.1. Assume that F is invertible. Then:

- (a) The sum of all entries of F^{-1} is $\frac{1}{\min \{x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_n\}}$.
- (b) Assume that $x_1 \leq x_2 \leq \dots \leq x_n$ and $y_1 \leq y_2 \leq \dots \leq y_n$ and $x_1 \leq y_1$. Then, for each $j \in \{1, 2, \dots, n\}$, the sum of all entries in the j -th column of F^{-1} is $\frac{1}{x_1}$ if $j = 1$, and is 0 if $j > 1$.

⁶This can be seen as an instance of tropicalization (see, e.g., [10]). More precisely, tropicalization (the sort that replaces $+$ and \cdot by \max and $+$) would replace $\frac{1}{x_i + y_j}$ by $-\max \{x_i, y_j\}$; but this turns into $\min \{x_i, y_j\}$ if we multiply all our numbers $x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_n$ by -1 .

The proof of this proposition is another neat exercise in working with inverse matrices – one we do not want to spoil for the reader. As with C , computing the determinant is not necessary. However, it is computable, and the result is another nice exercise:

Proposition 4.2. Assume that $x_1 \leq x_2 \leq \cdots \leq x_n$ and $y_1 \leq y_2 \leq \cdots \leq y_n$. For any $i, j \in \{1, 2, \dots, n\}$, set $f_{i,j} := \min \{x_i, y_j\}$. Then,

$$\det F = f_{1,1} \cdot \prod_{k=2}^n (f_{k,k} - f_{k,k-1} - f_{k-1,k} + f_{k-1,k+1}). \quad (2)$$

Note that the product on the right hand side of (2) will often be 0 if the x_i and the y_j 's are ordered in an “insufficiently balanced” way (e.g., if there are more than two y_j 's between two consecutive x_i 's). We leave it to the reader to establish more precise criteria for $\det F$ to be 0.

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