Math 504: Advanced Linear Algebra

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Math 504 Lecture 6

1. Schur triangularization (cont'd)

1.1. Application: Cayley–Hamilton theorem

Let us recall some properties of the characteristic polynomial of an $n \times n$ -matrix A:

Definition 1.1.1. Let \mathbb{F} be a field. Let $A \in \mathbb{F}^{n \times n}$ be an $n \times n$ -matrix over \mathbb{F} . The **characteristic polynomial** p_A of A is defined to be the polynomial

> $\det(tI_n - A) \in$ $\mathbb{F}[t]$ ring of all polynomials in the indeterminate twith coefficients in \mathbb{F}

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Example 1.1.2. Let n = 2 and $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. Then,

$$tI_n - A = tI_2 - A = t \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
$$= \begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix} - \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} t - a & -b \\ -c & t - d \end{pmatrix},$$

so that

$$p_A = \det(tI_n - A) = \det\begin{pmatrix}t - a & -b\\ -c & t - d\end{pmatrix} = (t - a)(t - d) - (-b)(-c)$$
$$= t^2 - (a + d)t + (ad - bc).$$

Example 1.1.3. Let
$$n = 3$$
 and $A = \begin{pmatrix} a & b & c \\ a' & b' & c' \\ a'' & b'' & c'' \end{pmatrix}$. Then,
 $tI_n - A = tI_3 - A = \begin{pmatrix} t - a & -b & -c \\ -a' & t - b' & -c' \\ -a'' & -b'' & t - c'' \end{pmatrix}$,

so that

$$p_A = \det \begin{pmatrix} t-a & -b & -c \\ -a' & t-b' & -c' \\ -a'' & -b'' & t-c'' \end{pmatrix}$$

= $t^3 - (a+b'+c'') t^2 + (ab'-ba'+ac''-ca''+b'c''-b''c') t$
- $(ab'c''-ab''c'-ba'c''+ba''c'+ca'b''-ca''b')$.

By the way, some authors define p_A to be det $(A - tI_n)$ instead of det $(tI_n - A)$. This differs from our definition only by a factor of $(-1)^n$, so the difference is insignificant.

Proposition 1.1.4 (properties of the char. poly.). Let \mathbb{F} be a field. Let $A \in \mathbb{F}^{n \times n}$ be an $n \times n$ -matrix over \mathbb{F} .

(a) The characteristic polynomial p_A is a monic polynomial in t of degree n. (That is, its leading term is t^n .)

(b) The constant term of p_A is $(-1)^n \det A$.

(c) The t^{n-1} -coefficient of p_A is $- \operatorname{Tr} A$. (Recall that $\operatorname{Tr} A$ is defined to be the sum of all diagonal entries of A; this is known as the **trace** of A.)

Proof. All of this should be more or less clear from the examples. Part (b) follows from observing that the constant term of p_A is $p_A(0) = \det(0I_n - A) = \det(-A) = (-1)^n \det A$.

For details, I'll give references in the notes.

Theorem 1.1.5 (Cayley–Hamilton theorem). Let \mathbb{F} be a field. Let $A \in \mathbb{F}^{n \times n}$ be an $n \times n$ -matrix. Then,

$$p_A(A) = 0.$$

(The "0" on the RHS is the zero matrix.)

Example 1.1.6. Let n = 2 and $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. Then, as we know,

$$p_A = t^2 - (a+d)t + (ad-bc).$$

Thus,

$$p_A(A) = A^2 - (a+d)A + (ad-bc)I_2$$

= $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^2 - (a+d)\begin{pmatrix} a & b \\ c & d \end{pmatrix} + (ad-bc)\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
= $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = 0.$

Remark 1.1.7. You cannot argue that $p_A(A) = \det(AI_n - A)$ "by substituting *A* for *t* into $p_A = \det(tI_n - A)$ ". Indeed, $tI_n - A$ is a matrix whose entries are polynomials in *t*. If you substitute *A* for *t* into it, it will become a matrix whose entries are matrices. First of all, it is not quite clear how to take the determinant of such a matrix; second, this matrix is not $AI_n - A$. For example, for n = 2, plugging *A* for *t* in $tI_n - A$ gives

$$\left(\begin{array}{ccc} \left(\begin{array}{cc} a & b \\ c & d \end{array}\right) - a & -b \\ & -c & \left(\begin{array}{cc} a & b \\ c & d \end{array}\right) - d \end{array}\right),$$

which doesn't quite look like $AI_n - A$ (which is the zero matrix). There is a correct proof of the Cayley–Hamilton theorem along the lines of "substituting A for t", but it requires a lot of work.

There are various proofs of the Cayley–Hamilton theorem (I'll give references in the notes). We will here only prove it for $\mathbb{F} = \mathbb{C}$:

Proof of the Cayley–Hamilton theorem for $\mathbb{F} = \mathbb{C}$ *.* Assume that $\mathbb{F} = \mathbb{C}$. The Schur triangularization theorem shows that *A* is unitarily similar to an upper-triangular

matrix. Hence, *A* is similar to an upper-triangular matrix (because unitarily similar matrices always are similar). In other words, there exists an invertible matrix *U* and an upper-triangular matrix *T* such that $A = UTU^{-1}$. Consider these *U* and *T*.

Now, let $\lambda_1, \lambda_2, ..., \lambda_n$ be the diagonal entries of *T*. Then, by Proposition 2.3.4, these diagonal entries $\lambda_1, \lambda_2, ..., \lambda_n$ are the eigenvalues of *A* (with algebraic multipliticies). Hence,

$$p_A = (t - \lambda_1) (t - \lambda_2) \cdots (t - \lambda_n)$$

(since p_A is monic, and the roots of p_A are precisely the eigenvalues of A with algebraic multiplicities).

Now, substituting *A* for *t* in the polynomial identity $p_A = (t - \lambda_1) (t - \lambda_2) \cdots (t - \lambda_n)$, we obtain

$$(A) = (A - \lambda_1 I_n) (A - \lambda_2 I_n) \cdots (A - \lambda_n I_n).$$

For each $i \in [n]$, we have

$$\underbrace{A}_{=UTU^{-1}} -\lambda_i \underbrace{I_n}_{=UU^{-1}} = UTU^{-1} - \lambda_i UU^{-1} = U(T - \lambda_i I_n) U^{-1}.$$

Hence, the above equality becomes

 p_A

$$p_A(A) = (A - \lambda_1 I_n) (A - \lambda_2 I_n) \cdots (A - \lambda_n I_n)$$

= $U(T - \lambda_1 I_n) \underbrace{U^{-1}U}_{=I_n} (T - \lambda_2 I_n) U^{-1} \cdots U(T - \lambda_n I_n) U^{-1}$
= $U(T - \lambda_1 I_n) (T - \lambda_2 I_n) \cdots (T - \lambda_n I_n) U^{-1}.$

Thus, it suffices to show that

$$(T - \lambda_1 I_n) (T - \lambda_2 I_n) \cdots (T - \lambda_n I_n) = 0.$$

Let us show this on an example for n = 3:

$$T = \begin{pmatrix} \lambda_1 & * & * \\ 0 & \lambda_2 & * \\ 0 & 0 & \lambda_3 \end{pmatrix}$$

$$\implies T - \lambda_1 I_n = \begin{pmatrix} 0 & * & * \\ 0 & \lambda_2 - \lambda_1 & * \\ 0 & 0 & \lambda_3 - \lambda_1 \end{pmatrix}$$

$$\implies (T - \lambda_1 I_n) (T - \lambda_2 I_n) = \begin{pmatrix} 0 & * & * \\ 0 & \lambda_2 - \lambda_1 & * \\ 0 & 0 & \lambda_3 - \lambda_1 \end{pmatrix} \begin{pmatrix} \lambda_1 - \lambda_2 & * & * \\ 0 & 0 & * \\ 0 & 0 & \lambda_3 - \lambda_1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & * \\ 0 & 0 & * \\ 0 & 0 & * \end{pmatrix}$$

$$\implies (T - \lambda_1 I_n) (T - \lambda_2 I_n) (T - \lambda_3 I_n) = \begin{pmatrix} 0 & 0 & * \\ 0 & 0 & * \\ 0 & 0 & * \end{pmatrix} \begin{pmatrix} \lambda_1 - \lambda_3 & * & * \\ 0 & \lambda_2 - \lambda_3 & * \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

The general proof follows the same pattern: Every time you add a new factor, one more column of your matrix becomes 0. Formally speaking, this means that you are proving the following fact by induction on *j*:

For each $j \in \{0, 1, ..., n\}$, the first j columns of the matrix

$$(T - \lambda_1 I_n) (T - \lambda_2 I_n) \cdots (T - \lambda_j I_n)$$

are 0.

Once this is proved, we can apply this to j = n, and conclude that the first n columns of the matrix

$$(T - \lambda_1 I_n) (T - \lambda_2 I_n) \cdots (T - \lambda_n I_n)$$

are 0. But this means that the whole matrix is 0, qed.

1.2. Sylvester's equation

Definition 1.2.1. Let $A \in \mathbb{C}^{n \times n}$. Then, the **spectrum** of *A* is defined to be the set of all eigenvalues of *A*. This spectrum is denoted by $\sigma(A)$ (or by spec *A*).

Theorem 1.2.2. Let *A* be an $n \times n$ -matrix, and let *B* be an $m \times m$ -matrix (both with complex entries). Let *C* be an $n \times m$ -matrix. Then, the following statements are equivalent:

- \mathcal{U} : There is a **unique** matrix $X \in \mathbb{C}^{n \times m}$ such that AX XB = C.
- \mathcal{V} : We have $\sigma(A) \cap \sigma(B) = \emptyset$.

Example 1.2.3. Let us take n = 1 and m = 1. In this case, *A*, *B* and *C* are 1×1 -matrices, so we can view them as scalars. Let us therefore write *a*, *b* and *c* for them. Then, the theorem says that the following statements are equivalent:

- \mathcal{U} : There is a **unique** complex number *x* such that ax xb = c.
- \mathcal{V} : We have $\{a\} \cap \{b\} = \emptyset$ (that is, $a \neq b$).

This is not surprising, because the equation ax - xb = c has a unique solution (namely, $x = \frac{c}{a-b}$) when $a \neq b$, and otherwise has either none or infinitely many solution.

The equation AX - XB = C in the Theorem is known as **Sylvester's equation**. Because the X is on different sides in AX and in XB, it cannot be factored out (matrices do not generally commute).

Proof of the $\mathcal{V} \Longrightarrow \mathcal{U}$ *part of the theorem.* First, observe that the matrix space $\mathbb{C}^{n \times m}$ is itself a \mathbb{C} -vector space of dimension *nm*.

Consider the map

$$L: \mathbb{C}^{n \times m} \to \mathbb{C}^{n \times m},$$
$$X \mapsto AX - XB.$$

This map *L* is linear, because

$$L (\alpha X + \beta Y) = A (\alpha X + \beta Y) - (\alpha X + \beta Y) B$$

= $\alpha AX + \beta AY - \alpha XB - \beta YB$
= $\alpha (AX - XB) + \beta (AY - YB) = \alpha L (X) + \beta L (Y).$

Thus, *L* is a linear map between two vector spaces that have the same (finite) dimension. Hence, we have the following equivalence:

$$(L \text{ is surjective } (= \text{ onto})) \\ \iff (L \text{ is injective } (= \text{ one-to-one})) \\ \iff (L \text{ is bijective } (= \text{ invertible})).$$

Now, statement \mathcal{U} is saying that the matrix C has a **unique** preimage under L (that is, there exists a unique $X \in \mathbb{C}^{n \times m}$ such that L(X) = C). As we know from general properties of linear maps, this is true whenever L is bijective, and false otherwise. So statement \mathcal{U} is equivalent to L being bijective.

Now, let us prove that $\mathcal{V} \Longrightarrow \mathcal{U}$. To wit, we will show that *L* is **injective**. This will imply that *L* is bijective (by the above equivalence), and therefore statement \mathcal{U} will follow.

In order to prove that a linear map is injective, it suffices to show that its kernel (= nullspace) is 0. So let $X \in \text{Ker } L$; we will show that X = 0.

From $X \in \text{Ker } L$, we get L(X) = 0. Since L(X) = AX - XB, this means that AX - XB = 0. In other words, AX = XB. Hence,

$$A^2X = A \underbrace{AX}_{=XB} = \underbrace{AX}_{=XB} B = XBB = XB^2.$$

Similarly,

$$A^3X = XB^3, \qquad A^4X = XB^4, \qquad A^5X = XB^5, \qquad \dots$$

That is,

 $A^k X = X B^k$ for each $k \in \mathbb{N}$.

(Strictly speaking, this is proved by induction on *k*.)

Therefore, I claim that

f(A) X = X f(B) for any polynomial $f \in \mathbb{C}[t]$.

(Indeed, if we write the polynomial f as $f = \sum_{k=0}^{m} f_k t^k$ with $f_k \in \mathbb{C}$, then

$$f(A) X = \sum_{k=0}^{m} f_{k} \underbrace{A^{k} X}_{=XB^{k}} = \sum_{k=0}^{m} f_{k} XB^{k} = X \underbrace{\sum_{k=0}^{m} f_{k} B^{k}}_{=f(B)} = Xf(B),$$

as desired.)

Apply this claim to $f = p_A$. We obtain

$$p_A(A) X = X p_A(B) = X (B - \lambda_1 I_n) (B - \lambda_2 I_n) \cdots (B - \lambda_n I_n),$$

where $\lambda_1, \lambda_2, ..., \lambda_n$ are the eigenvalues of *A* (with algebraic multiplicities), because

$$p_A = (t - \lambda_1) (t - \lambda_2) \cdots (t - \lambda_n).$$

Thus,

$$X (B - \lambda_1 I_n) (B - \lambda_2 I_n) \cdots (B - \lambda_n I_n) = \underbrace{p_A(A)}_{\text{(by Cayley-Hamilton)}} X = 0.$$

We want to prove that X = 0. This would follow from this equation if we knew that the factors

$$B - \lambda_1 I_n, B - \lambda_2 I_n, \ldots, B - \lambda_n I_n$$

are invertible (because then we can cancel these factors). However, they are indeed invertible, because each λ_i is an eigenvalue of A and therefore **not** an eigenvalue of B (since $\sigma(A) \cap \sigma(B) = \emptyset$). This completes the proof of $\mathcal{V} \Longrightarrow \mathcal{U}$.

Maybe $\mathcal{U} \Longrightarrow \mathcal{V}$ will be homework. Also a nice exercise(?):

$$\sigma(L) = \sigma(A) - \sigma(B) = \{\lambda - \mu \mid \lambda \in \sigma(A) \text{ and } \mu \in \sigma(B)\}.$$