

Fix λ commutative ring K . (for example, $K = \mathbb{Z}$ or $\mathbb{Q}$ or $\mathbb{R}$ or $\mathbb{C}$.) ①

Def. A formal power series (FPS) (in 1 indeterminate x over K) is a sequence $(a_0, a_1, \dots) \in K^\infty$ of elements of K .

This might answer "what is an FPS", but does not explain what we can do with FPSs. For example, why can we write $(a_0, a_1, a_2, \dots)$ as

$$a_0 + a_1 x + a_2 x^2 + \dots? \text{ What is } x?$$

Def. (a) The sum of two FPS $(a_0, a_1, \dots)$ and $(b_0, b_1, \dots)$ is $(a_0 + b_0, a_1 + b_1, \dots)$.

(b) If $\lambda \in K$ and $(a_0, a_1, \dots)$ is a FPS, then $\lambda(a_0, a_1, \dots)$ is defined as $(\lambda a_0, \lambda a_1, \dots)$.

(c) The product of two FPS $(a_0, a_1, \dots)$ and $(b_0, b_1, \dots)$ is the FPS $(c_0, c_1, \dots)$, where

$$c_n = \sum_{i=0}^n a_i b_{n-i} = \sum_{\substack{i, j \in \mathbb{N}; \\ i+j=n}} a_i b_j = a_0 b_n + a_1 b_{n-1} + \dots + a_n b_0.$$

(d) For each $a \in K$, define the FPS $\underline{a} = (a, 0, 0, \dots)$. (2)
 We'll soon just call it $\underline{a}$, but for now let's use $\underline{a}$.

(e) The set of all FPS is called $K[[x]]$. (Double square brackets.)

Thm. 1. $K[[x]]$ is a comm. ring, with subring K (if we regard each $a \in K$ as the FPS $\underline{a}$). Specifically, this means:

(a) Addition in $K[[x]]$ is commutative & associative:

$$\underline{a} + (\underline{b} + \underline{c}) = (\underline{a} + \underline{b}) + \underline{c},$$

$$\underline{a} + \underline{b} = \underline{b} + \underline{a},$$

(b) $\underline{0} + \underline{a} = \underline{a} + \underline{0} = \underline{a}.$

(c) Multiplication in $K[[x]]$ is commutative & associative:

$$\underline{a}(\underline{b}\underline{c}) = (\underline{a}\underline{b})\underline{c},$$

$$\underline{a}\underline{b} = \underline{b}\underline{a},$$

(d) $\underline{1}\underline{a} = \underline{a}\underline{1} = \underline{a}.$

(e) $\underline{0}\underline{a} = \underline{a}\underline{0} = \underline{0}.$

(f) Distributivity holds: $\underline{a}(\underline{b} + \underline{c}) = \underline{a}\underline{b} + \underline{a}\underline{c}$, $(\underline{a} + \underline{b})\underline{c} = \underline{a}\underline{c} + \underline{b}\underline{c}.$

(g) $\forall \underline{a}, \underline{b} \in K[[x]]$ there is a unique $\underline{c}$ (called $\underline{a} - \underline{b}$) with

$$\underline{a} - \underline{b} = \underline{c} + \underline{b}. \quad (\text{This is quite easy: } (a_0, a_1, \dots) - (b_0, b_1, \dots) = (a_0 - b_0, a_1 - b_1, \dots).)$$

(h) $\forall a, b \in K$ we have $\underline{a+b} = \underline{a+b}$ and $\underline{a \cdot b} = \underline{a \cdot b}$. (3)

~~add~~

Furthermore, $K[x]$ is a K -module (same as K -vector space, except K doesn't have to be a field). That is,

$$(i) \quad \lambda(\vec{a} + \vec{b}) = \lambda\vec{a} + \lambda\vec{b},$$

$$(j) \quad (\lambda + \mu)\vec{a} = \lambda\vec{a} + \mu\vec{a},$$

$$(k) \quad (\lambda\mu)\vec{a} = \lambda(\mu\vec{a}),$$

$$(l) \quad 1\vec{a} = \vec{a}.$$

Finally:

$$(m) \quad \lambda\vec{a} = \underline{\lambda} \cdot \vec{a} \quad \forall \lambda \in K \text{ and } \vec{a} \in K[x].$$

The purpose of Thm. 1 is to justify computing with FPS as with numbers, at least as far as $+$, $-$ and $\cdot$ are concerned.

Knowing that $K[x]$ is a comm. ring implies:

Knowing that

- subtraction works

- sums & products need no parentheses and don't care about the order: for example, $((\vec{a}\vec{b})\vec{c})\vec{d} = \vec{a}((\vec{b}\vec{c})\vec{d}) = \vec{a}(\vec{b}\vec{c}\vec{d})$

④

$\vec{a}(\vec{b}(\vec{c}\vec{d}))$, so we can denote all of these by $\vec{a}\vec{b}\vec{c}\vec{d}$. Also, $\vec{a}\vec{b}\vec{c}\vec{d} = \vec{b}\vec{d}\vec{c}\vec{a} = \vec{c}\vec{a}\vec{b}\vec{d}$.

Hence, finite sums & products work as usual: $\sum_{i=1}^k \vec{a}_i$, $\sum_{i \in I} \vec{a}_i$,

$\prod_{i=1}^k \vec{a}_i$, $\prod_{i \in I} \vec{a}_i$. These can be computed in any order,

In particular, powers exist: $\vec{a}^n = \underbrace{\vec{a}\vec{a} \cdots \vec{a}}_{n \text{ times}} \quad \forall n \in \mathbb{N}$.

This includes $\vec{a}^0 = \underline{1}$.

Standard rules for exponents hold: $\vec{a}^{nm} = \vec{a}^n \vec{a}^m$,

$(\vec{a}\vec{b})^n = \vec{a}^n \vec{b}^n$, etc.

$(\vec{a} + \vec{b})^n = \sum_{k=0}^n \binom{n}{k} \vec{a}^{n-k} \vec{b}^k$.

The binomial formula holds: $(\vec{a} + \vec{b})^n = \sum_k \binom{n}{k} \vec{a}^{n-k} \vec{b}^k$.

All other kinds of formulas hold, e.g. Vandermonde: $\binom{\vec{a} + \vec{b}}{n} = \sum_k \binom{\vec{a}}{k} \binom{\vec{b}}{n-k}$.

(Recall $\binom{x}{n} = \frac{x(x-1) \cdots (x-n+1)}{n!}$.)

if $K = \mathbb{Q}, \mathbb{R}$ or $\mathbb{C}$.

Def. $\forall n \in \mathbb{N}$ and $\vec{a} = (a_0, a_1, \dots) \in K[[x]]$, we set $[x^n] \vec{a} = a_n$. (5)

This is called the coefficient of x^n in $\vec{a}$.

Thus, the definition of sum & product rewrite as follows:

$$(1) \quad [x^n](\vec{a} + \vec{b}) = [x^n] \vec{a} + [x^n] \vec{b},$$

$$(2) \quad [x^n](\vec{a} \vec{b}) = [x^0] \vec{a} \cdot [x^n] \vec{b} + [x^1] \vec{a} \cdot [x^{n-1}] \vec{b} + \dots$$

$$(3) \quad = \sum_{i=0}^n [x^i] \vec{a} \cdot [x^{n-i}] \vec{b}$$

$$(4) \quad = \sum_{j=0}^n [x^{n-j}] \vec{a} \cdot [x^j] \vec{b}$$

Proof of Thm. 1. Most parts are straightforward.

$$(c) \quad \text{Associativity: } [x^n](\vec{a} \vec{b} \vec{c}) \stackrel{(4)}{=} \sum_{j=0}^n [x^{n-j}] (\vec{a} \vec{b}) \cdot [x^j] \vec{c}$$

$$\stackrel{(2)}{=} \sum_{i=0}^n [x^i] \vec{a} \cdot [x^{n-i-j}] \vec{b}$$

$$= \sum_{j=0}^n \sum_{i=0}^{n-j} [x^i] \vec{a} \cdot [x^{n-i-j}] \vec{b} \cdot [x^j] \vec{c},$$

whereas

6

$$\begin{aligned}
 [x^n](\vec{a}(\vec{b}\vec{c})) &\stackrel{(3)}{=} \sum_{i=0}^n [x^i]\vec{a} \cdot \underbrace{[x^{n-i}](\vec{b}\vec{c})}_{(4)} \\
 &\stackrel{(4)}{=} \sum_{j=0}^{n-i} [x^{n-i-j}]\vec{b} \cdot [x^j]\vec{c} \\
 &= \sum_{i=0}^n [x^i]\vec{a} \cdot \sum_{j=0}^{n-i} [x^{n-i-j}]\vec{b} \cdot [x^i]\vec{c}.
 \end{aligned}$$

The RHSes are equal, since

$$\sum_{j=0}^n \sum_{i=0}^{n-j} = \sum_{\substack{i,j \in \mathbb{N}; \\ i+j \leq n}} = \sum_{i=0}^n \sum_{j=0}^{n-i}$$

and $n-j-i = n-i-j$. Thus, $[x^n](\vec{a}\vec{b}\vec{c}) = [x^n](\vec{a}(\vec{b}\vec{c}))$
 $\forall n \in \mathbb{N}$. Hence, $(\vec{a}\vec{b})\vec{c} = \vec{a}(\vec{b}\vec{c})$, since a FPS is just
 the sequence of its coefficients. $\square$

Sometimes, ∞ sums also make sense in $K[[x]]$.

Example:

$$\begin{aligned}
 & (1, 1, 1, 1, 1, 1, 1, \dots) \\
 & + (0, 1, 1, 1, 1, 1, 1, \dots) \\
 & + (0, 0, 1, 1, 1, 1, 1, \dots) \\
 & + (0, 0, 0, 1, 1, 1, 1, \dots) \\
 & + \dots \\
 & = (1, 2, 3, 4, 5, 6, 7, 8, \dots)
 \end{aligned}$$

Def. A (possibly infinite) family $(\vec{a}_i)_{i \in I}$ of FPSs is summable if $\forall n \in \mathbb{N}$, only finitely many $i \in I$ satisfy $[x^n] \vec{a}_i \neq 0$.

In this case, the sum $\sum_{i \in I} \vec{a}_i$ is defined as the FPS with

$$[x^n] \left(\sum_{i \in I} \vec{a}_i \right) = \sum_{i \in I} [x^n] \vec{a}_i \quad \forall n \in \mathbb{N}.$$

a sum with only

finitely many
nonzero addends,

hence well-defined in K

Rmk.: (5) $\nLeftrightarrow \forall n \in \mathbb{N}$, infinitely many $i \in \mathbb{I}$ satisfy $[x^n] \vec{a}_i = 0$. ⑧

Prop. 2: Sums of summable families satisfy the usual rules for summation (as long as all families involved are summable), with the exception of "interchange of Σ signs":

EX. Here is this exception (in $\mathbb{Z}$):

Set $a_{i,j} = [i=j] - [i+1=j]$ for all $i, j \in \{1, 2, 3, \dots\}$.

So

$i \backslash j$	1	2	3	4	5	...
1	1	-1				
2		1	-1			
3			1	-1		
4				1	-1	

Then

$$\sum_{i=1}^{\infty} \sum_{j=1}^{\infty} a_{i,j} = \sum_j 0 = 0 \quad \text{but} \quad \sum_{j=1}^{\infty} \sum_{i=1}^{\infty} a_{i,j} = \sum_j [j=1] = 1$$

$\underbrace{\sum_{i=1}^{\infty} a_{i,j}}_{=0}$
 $\underbrace{\sum_{i=1}^{\infty} a_{i,j}}_{=[j=1]}$

But we can fix this if we require the whole family $(a_{ij})_{(i,j) \in \mathbb{N}^2}$ to be summable. (9)

"Discrete Fubini's theorem": If $(\vec{a}_{ij})_{(i,j) \in I \times J}$ is a summable family of FPS, then

$$\sum_{i \in I} \sum_{j \in J} \vec{a}_{ij} = \sum_{(i,j) \in I \times J} \vec{a}_{ij} = \sum_{j \in J} \sum_{i \in I} \vec{a}_{ij}.$$

Def. x denotes the FPS $(0, 1, 0, 0, 0, \dots)$.
So this is our answer to "what is x ?"

Prop. 3. $x^k = (0, 0, \dots, 0, \underbrace{1}_{k \text{ zeroes}}, 0, 0, 0, \dots) \quad \forall k \in \mathbb{N}.$

Proof. Induct over k , by observing that if $\vec{a} = (a_0, a_1, a_2, \dots)$, then $x\vec{a} = (0, a_0, a_1, a_2, \dots)$.

Cor. 4. Any FPS $(a_0, a_1, \dots) \in K[[x]]$ satisfies $(a_0, a_1, \dots) = a_0 + a_1 x + a_2 x^2 + \dots = \sum_{n \in \mathbb{N}} a_n x^n.$

In particular, the RHS is well-defined, i.e., the family $(a_n x^n)_{n \in \mathbb{N}}$ is summable.

Proof.

$$\begin{aligned}
 a_0 + a_1 x + a_2 x^2 + \dots &= (a_0, 0, 0, \dots) \\
 &+ (0, a_1, 0, \dots) \\
 &+ (0, 0, a_2, \dots) \\
 &+ (0, 0, 0, a_3, \dots) \\
 &= (a_0, a_1, a_2, a_3, \dots)
 \end{aligned}$$

No analysis was used to make these power series well-defined! □

Now, we have learned

- what FPS are,
- how to do basic algebra with them $(+, -, \cdot)$,
- what x is,
- why we can compare coefficients (i.e., why $\sum_{n \in \mathbb{N}} a_n x^n = \sum_{n \in \mathbb{N}} b_n x^n$ implies $a_k = b_k \forall k$).

In particular, Example 3 is now justified.

(11)
We don't yet know:

- what we can substitute into a FPS;
- when & why can we do fancier algebra (like solving quadratic equations, or dividing).

So, the remaining examples are still hanging loose.

Def. let $\vec{a} \in K[x]$. A multiplicative inverse of $\vec{a}$ means a FPS $\vec{b} \in K[x]$ such that $\vec{a}\vec{b} = \vec{b}\vec{a} = \underline{1}$.

Thm. 5. let $\vec{a} \in K[x]$. Then, there is at most 1 multiplicative inverse of $\vec{a}$.

Proof. let $\vec{b}$ and $\vec{c}$ be two mult. inverses of $\vec{a}$. Then,
 $\vec{a}\vec{b} = \vec{b}\vec{a} = \underline{1}$ and $\vec{a}\vec{c} = \vec{c}\vec{a} = \underline{1}$.

$$\begin{aligned} \vec{b}(\vec{a}\vec{c}) &= \vec{b}\underline{1} = \vec{b} \\ \text{but } (\vec{b}\vec{a})\vec{c} &= \underline{1}\vec{c} = \vec{c}, \end{aligned}$$

so by associativity the LHSs are equal. So the RHSs are equal, $\square$
so $\vec{b} = \vec{c}$.

Def. The mult. inverse of $\vec{a}$ (if it $\exists$) is called $\vec{a}^{-1}$ or $1/\vec{a}$.

Thm. 6. let $a \in K[x]$. Then a has a multiplicative inverse $\iff [x^0]a$ has a mult. inverse in K .

Rmk. What numbers have multiplicative inverses in K ?

• If $K = \mathbb{Z}$, then ± 1 only.

• If $K = \mathbb{Q}$, then all nonzero numbers.

• If $K = \mathbb{R}$, then $\text{---} \text{---} \text{---}$

• If $K = \mathbb{C}$, then $\text{---} \text{---} \text{---}$

$$\left(\frac{1}{a+bi} = \frac{a-bi}{a^2+b^2} \right)$$

$\Rightarrow \mathbb{Q}, \mathbb{R}, \mathbb{C}$ are
fields

Proof of Thm. 6. $\Rightarrow$: easy:

Write a as $(a_0, a_1, a_2, \dots)$.

We're assumed $\exists b = (b_0, b_1, b_2, \dots)$ with $ab = 1$.

$$\text{So } (1, 0, 0, \dots) = 1 = ab = (a_0, a_1, \dots)(b_0, b_1, \dots)$$

$$= (a_0 b_0, \text{---} \text{---} \text{---}, \text{whatever}).$$

$$\text{So } 1 = a_0 b_0 \Rightarrow a_0 \text{ has a mult. inverse in } K \text{ (namely, } b_0 \text{).} \checkmark$$

$$[x^0]a$$

$\Leftarrow$: Write ~~Set~~ a as $a = (a_0, a_1, a_2, \dots)$, and (13)
 we're looking for a FPS $b = (b_0, b_1, b_2, \dots)$ with $ab = 1$.

So we want

$$\begin{aligned} (1, 0, 0, \dots) &= 1 = ab = (a_0, a_1, a_2, \dots)(b_0, b_1, b_2, \dots) \\ &= (a_0 b_0, a_0 b_1 + a_1 b_0, a_0 b_2 + a_1 b_1 + a_2 b_0, \dots) \end{aligned}$$

So we want

$$\begin{cases} 1 = a_0 b_0 \\ 0 = a_0 b_1 + a_1 b_0 \\ 0 = a_0 b_2 + a_1 b_1 + a_2 b_0 \\ 0 = a_0 b_3 + a_1 b_2 + a_2 b_1 + a_3 b_0 \\ \vdots \end{cases}$$

Solve this system by elimination: get b_0 from 1st eqn,

then b_1 from the next,

This is possible, since $a_0 = [x^0]a$ has a mult. inverse, so it
 can be divided by. $\checkmark$ 7